Task assignment

1. **ZhaoKe: Abstract, Introduction, background and related Work, system model, problem formulation.**
2. **Kaixin: Technical Approach (Method)**
   1. Introduce decision transformer in our environment.

State: Current UAVs location

Action: Next step of UAVs

Reward:

1. **Steve: Experimental Results (including Dataset)**
   1. Compare with SOTA method (PPO,A2C…) in different number of users(20,30,40,50) and check the system delay.
   2. Compare in different UAV coverage.
   3. Example of UAV trajectories in different method.
2. **Together: Conclusion, Author Contributions**